

Standard specifications

<u>KJ194UTE35</u> <u>KJ194UVE35</u>

1st Edition: August 10, 2018

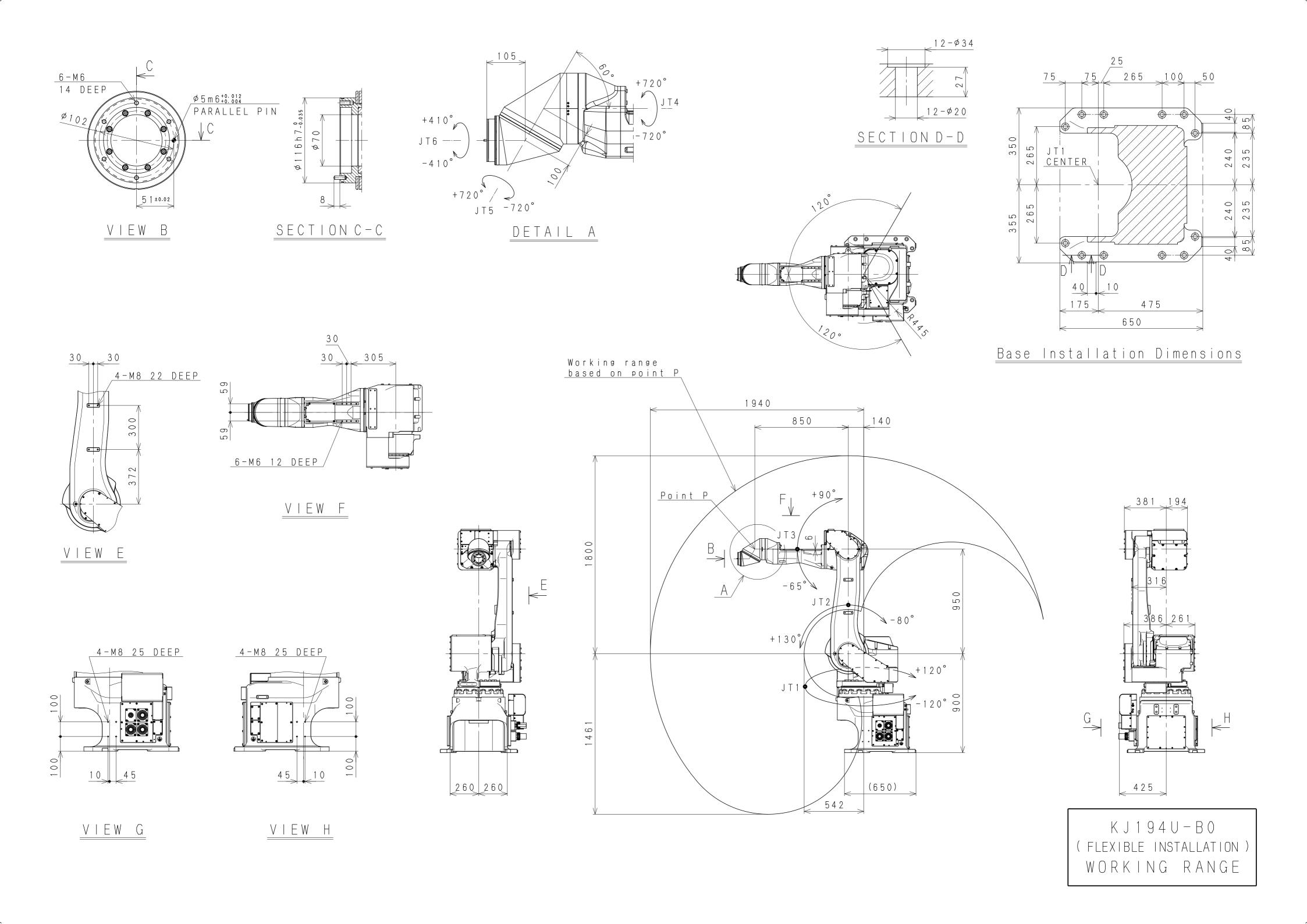
KAWASAKI HEAVY INDUSTRIES, LTD. ROBOT DIVISION

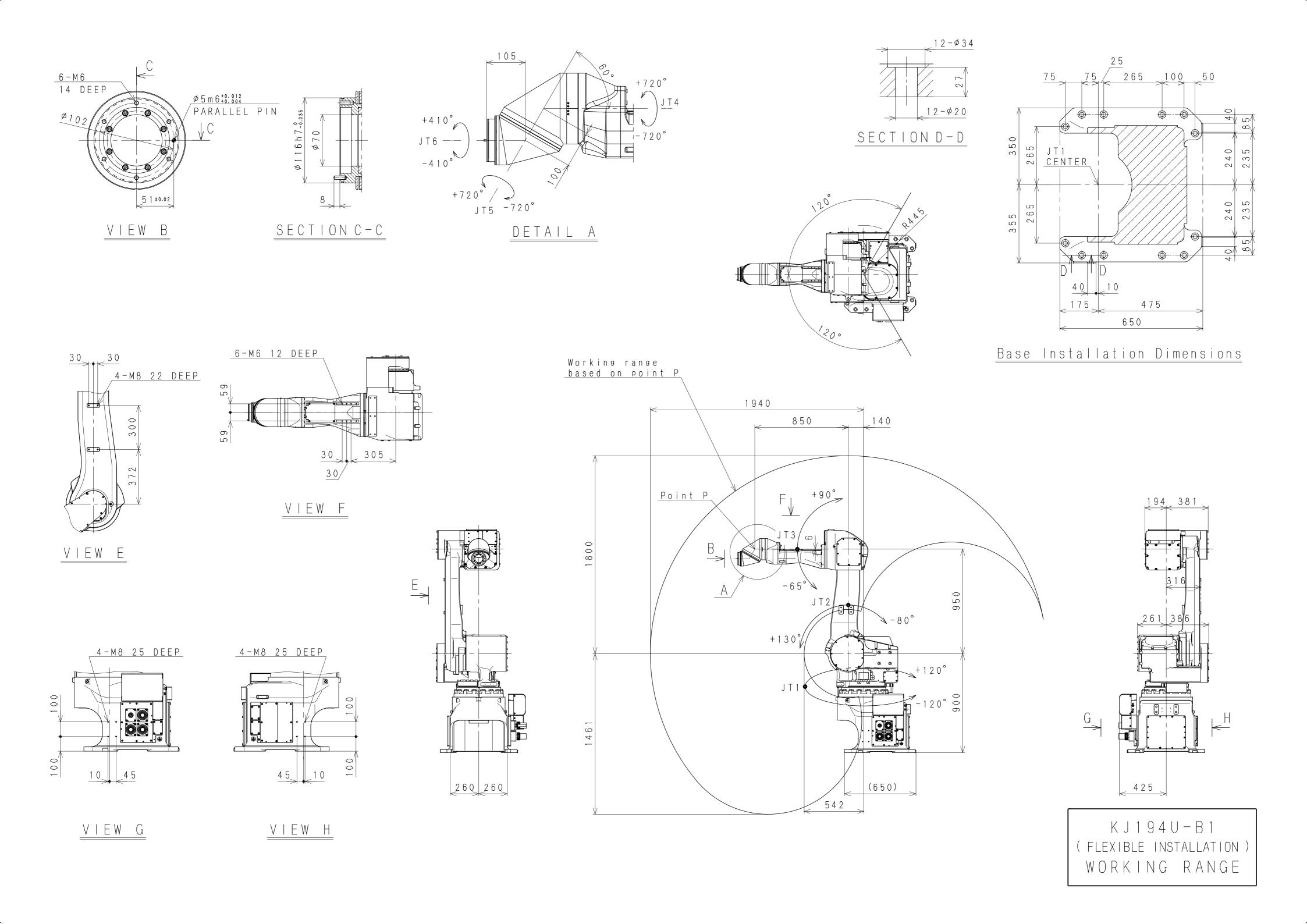
Specification:	90101-2539DEA
(Arm):	90151-0081DEC
(Controller):	90152-0059DEA

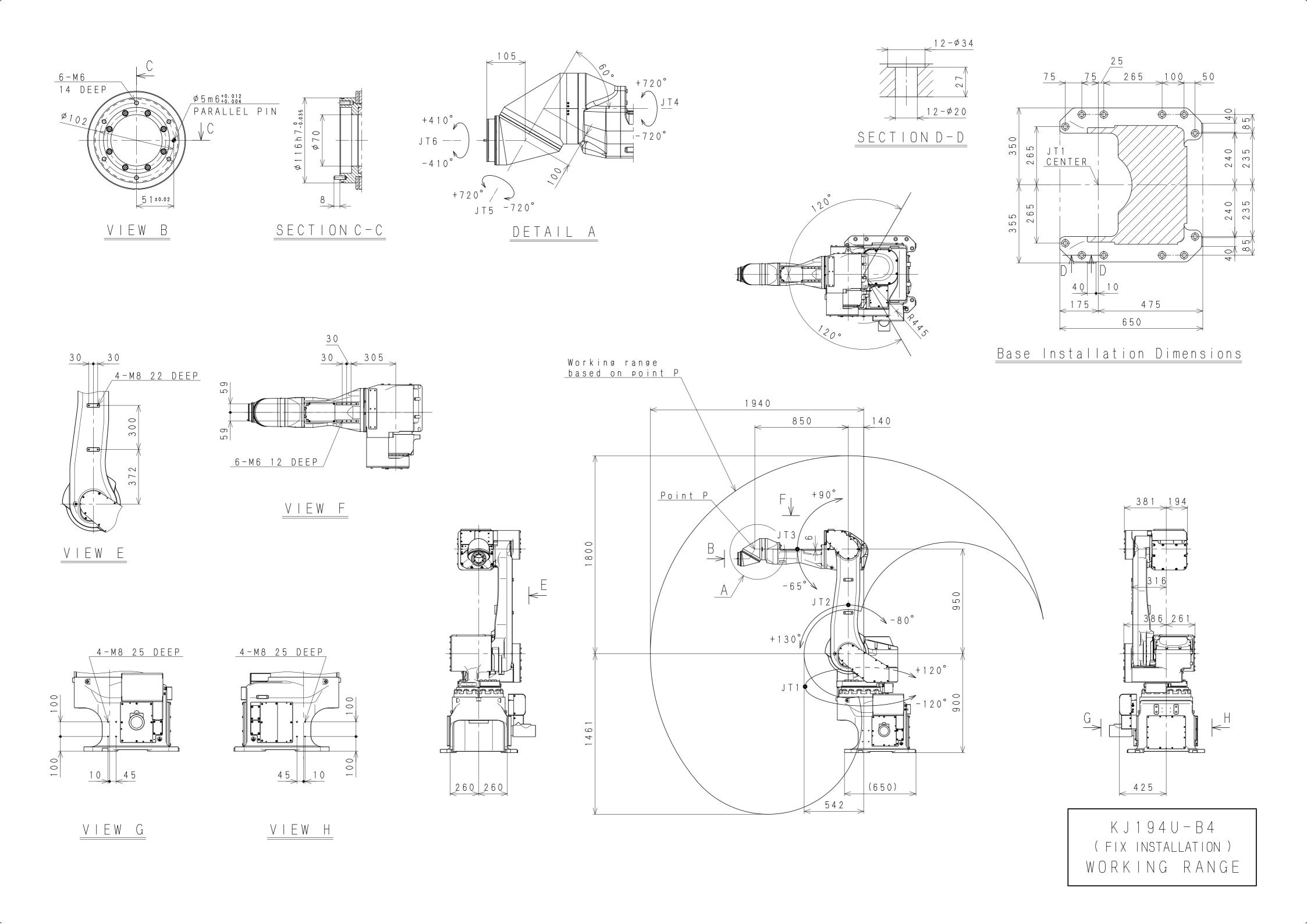
1. Specification of Robot

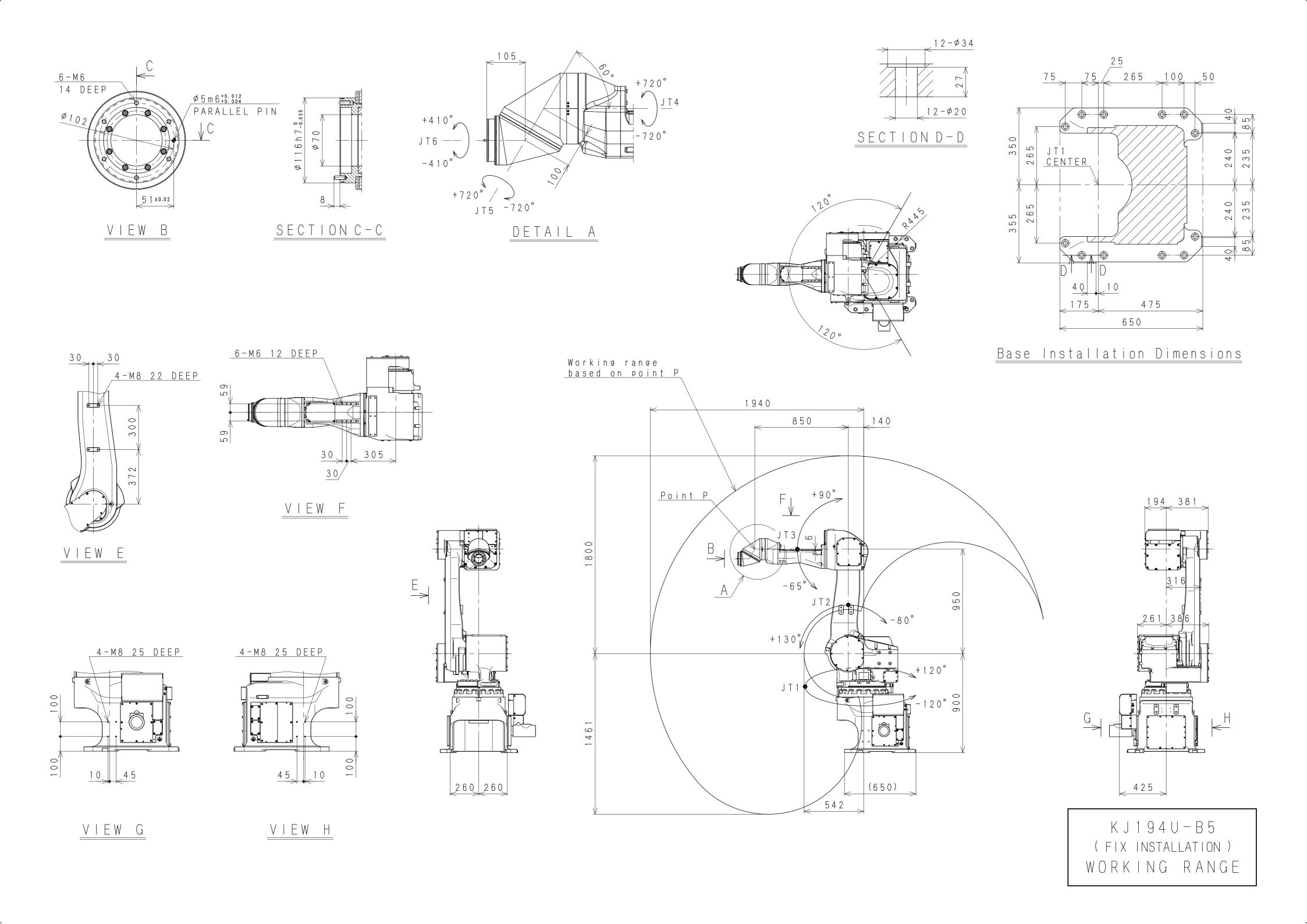
[1] Robot Arm (KJ194U)	0001						
1. Model	Model						
		Installation mode	Fix Installation			Flexible Installation	
			Standard	Mirror	Standard	Mirror	
		Floor	KJ194U-B4	KJ194U-B5	KJ194U-B0	KJ194U-B1	
	M	ounting wall is left side	KJ194U-D4	KJ194U-D5	KJ194U-D0	KJ194U-D1	
	Mo	ounting wall is right side		KJ194U-F5	KJ194U-F0	KJ194U-F1	
		Shelf	KJ194U-H4	KJ194U-H5	KJ194U-H0	KJ194U-H1	
2. Type	Articulated robot						
3. Degree of freedom	6 axes						
4. Axis specification	Opera Arm rotation	Max. operating range KJ194U-B \Box +120 $^{\circ}$ \sim -120 $^{\circ}$					
	Aim iotation	(JT1)	KJ194U-B□ $+120^{\circ} \sim -120^{\circ}$ KJ194U-D□ $+120^{\circ} \sim -30^{\circ}$				
			KJ194U			~-120°	
			KJ194U			~-120°	
	Arm out-in	(JT2)			0° ∼− 80°		
	Arm up-down				$0^{\circ} \sim -65^{\circ}$		
	Wrist roll Wrist roll	(JT4) (JT5)			$0^{\circ} \sim -720^{\circ} \ 0^{\circ} \sim -720^{\circ}$		
	Wrist roll	(JT6)			$\frac{0^{\circ} \sim -720}{0^{\circ} \sim -410^{\circ}}$		
5. Repeatability		tool mounting surface)	171	. 110		
6. Max. payload		the tool mounting sur					
	Upper arm: 25 k	-					
7. 16. 1		er Arm :Include paint		in pressurize	d compartmen	t)	
7. Max. painting speed8. Load capacity of wrist	1500 mm/s (at th	e center of tool moun	ting surface)				
8. Load capacity of wrist	Max. torque Moment of inertia [*]					nent of inertia*	
	JT4		56.2 N·m		2.19 kg·m ²		
	JT5	43	3.4 N∙m		$1.31 \text{ kg} \cdot \text{m}^2$		
	JT6						
	Note* Each value in this table shows allowable payload moment of inertia of JT4/JT5/JT6 when max.						
		r your application, please					
	contact K	Kawasaki.					
Driving motor	Brushless AC Se	rvomotor					
10. Working range	See attached drav	wing			2001 (11		
11. Mass	KJ194U-B 530 kg (without options)						
12. Color	KJ194U -D□ ,-F□ , -H□						
13. Installation	KJ194U-B□(Flo			KJ194U-D□	(Mounting wa	all is left side)	
		KJ194U-F□(Mounting wall is right side) KJ194U-H□(Shelf)					
	KJ194U-□4, K.				l on fixed plan		
14. Environment cond.	KJ194U-□0, K.				nstall on trave	erse unit)	
14. Environment cond. 15. Explosion proof	(Temperature) $0 \sim 40$ °C, (Humidity) $35 \sim 85$ %, no dew, nor frost allowed Pressurized and intrinsically safe						
16. Air supply		$0.5 \text{ Nm}^3/\text{min}, 0.4 \sim 0$.7 MPa				
to the manipulator		Dew point : -17°		ospheric pres	sure.		
	Solid material: 0.01 μm or less						
17 Ontions	Adiyatahla Mari	Oil content: Mist separation 99.9999% or more					
17. Options	Adjustable Mechanical Stopper: JT1/JT2/JT3						
	Painting equipment FGP motor (1 unit can be equipped with) Solenoid valve for painting (up to 3 units can be equipped with)						
	Electro pneumatic converter for painting (up to 3 units can be equipped with) Upper Arm cover						
18. Others	Consult Kawasak	ki about maintenance	parts and spare	parts.			
-3. 3	Compart Trawasar	IIIIIIIIIIIIIIII	and spare	F 32 00.			

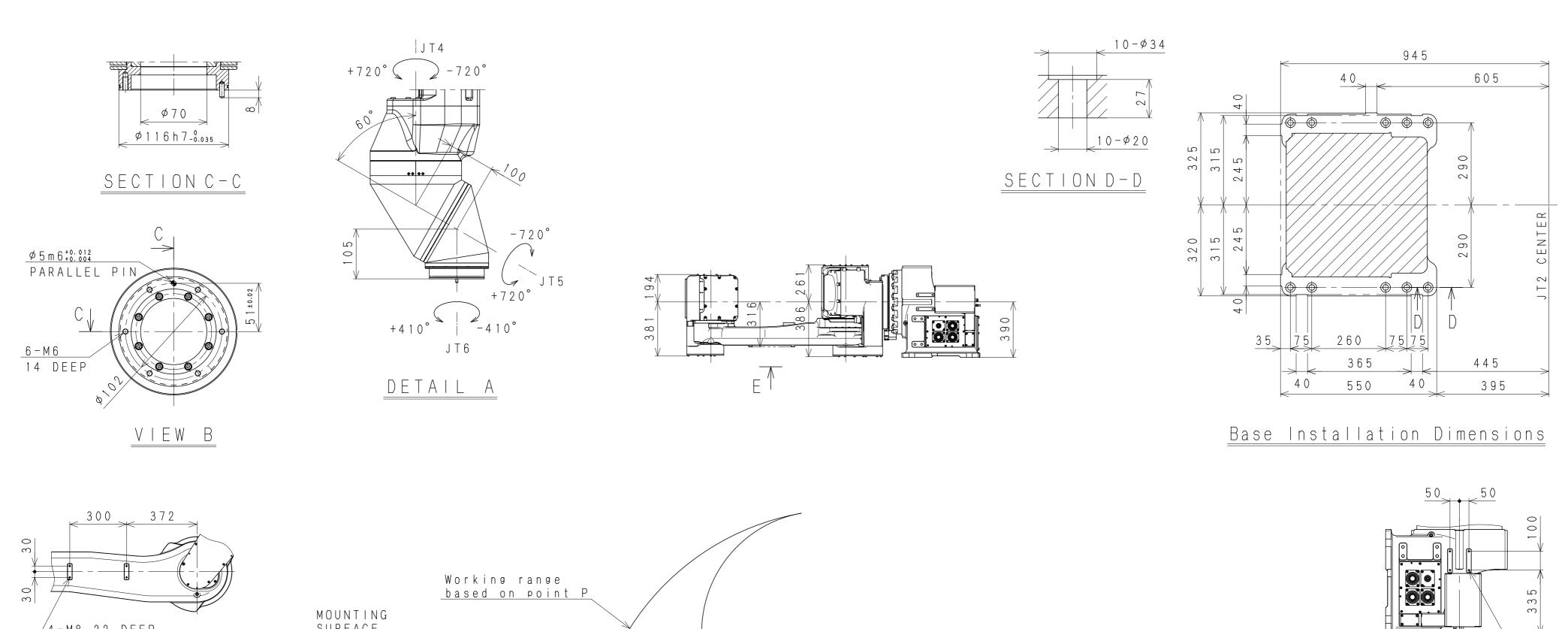
[2] Controller						
1. Model	E35/E37					
2. Enclosure	Enclosed structure /	Indirect cooling system				
3. Dimensions	See attached drawing					
4. Number of controlled	6 axes	i				
axes	7/8/9 axes(built-in addition, option)					
5. Servo control and		Full Digital Servo System				
drive system		Tuli Digital Sci vo System				
6. Type of control	Teach mode Joint, Base, Tool, Fixed Tool (option) operation mode					
	Repeat mode PTP, CP control mode					
		Joint, Linear, Circular (option) interpolation				
7. Teaching method	Teaching or AS lang	•				
8. Memory capacity	8 MB					
9. External operation	External Motor Power Off, External Hold, etc.					
signals						
10. General purpose	Input signals	32 channels (Includes dedicat	dicated signals)			
signals	Output signals	32 channels (Includes dedicat	ed signals)			
11. Operation panel	Basic Operation Switches					
	(Teach/Repeat SW, Emergency Stop SW, Control power lamp)					
12. Cable length		n non hazardous area	3 m			
	Power/Signal cable i		3 m			
	Teach Pendant cable	:	10 m			
13. Mass		See attached drawing				
14. Power requirement	AC 440 - 480 V±109	•				
	Max 5.1 kVA(E37), Max 7.3 kVA(E35)					
15. Ground	PE (Standard for Robots)					
	Leakage current: max. 10 mA					
16. Ambient temperature	0 - 45 °C					
17. Relative humidity	35 - 85 % (non-condensation)					
18. Color	Munsell: 10GY9/1 equivalent					
19. Ex. Light Weight Teach Pendan						
20 Ontions	Emergency Stop, 1 ea	ach Lock and Enable Switches				
20. Options General purpose	Input signals 64/96/128 channels (Includes dedicated signals)					
signals	Input signals		<u> </u>			
I/O connector	Output signals 64/96/128 channels (Includes dedicated signals) D. SUB 37pin(male female) with cover					
Operation panel	D-SUB 37pin(male,female) with cover Motor Power ON, Cycle start, RUN/HOLD, Error reset, Error lamp					
Power/Signal cable		ea 5,7,10,15,20,25,30m	Dio imip			
Tower/Bighar cable	in hazardous area 1,5,7,10,15,20,25,30 Total length: max. 40 m					
Teach Pendant cable	3,5,7,10,15,20,25,30		Tomi lengui. mun. To m			
Teach pendant	in non hazardous are					
Connector Box	in hazardous area 1,3,5,7,10,15m Total length: max. 30 m					
Power requirement	AC 380 - 415 V, AC 440 - 480 V, AC 515 V, AC 575 V ±10%, 50/60 Hz, 3 phases,					
4"	Max 7.3 kVA(E35/E37)					
Auxiliary storage	USB memory					
AC Outlet	AC110 - 120V Outlet (depends on Primary input voltage)					
PC cable	1.5m, 3m					
Teach Pendant option	Cable hook, connector for TP less					
Others	LED Light, Field BUS, Software PLC, Analog input/output,					
Onicis	LED Light, Field BU	JS, Software PLC, Analog input	/output,			
Outers		JS, Software PLC, Analog input zation, Paint Equipment Contro	-			

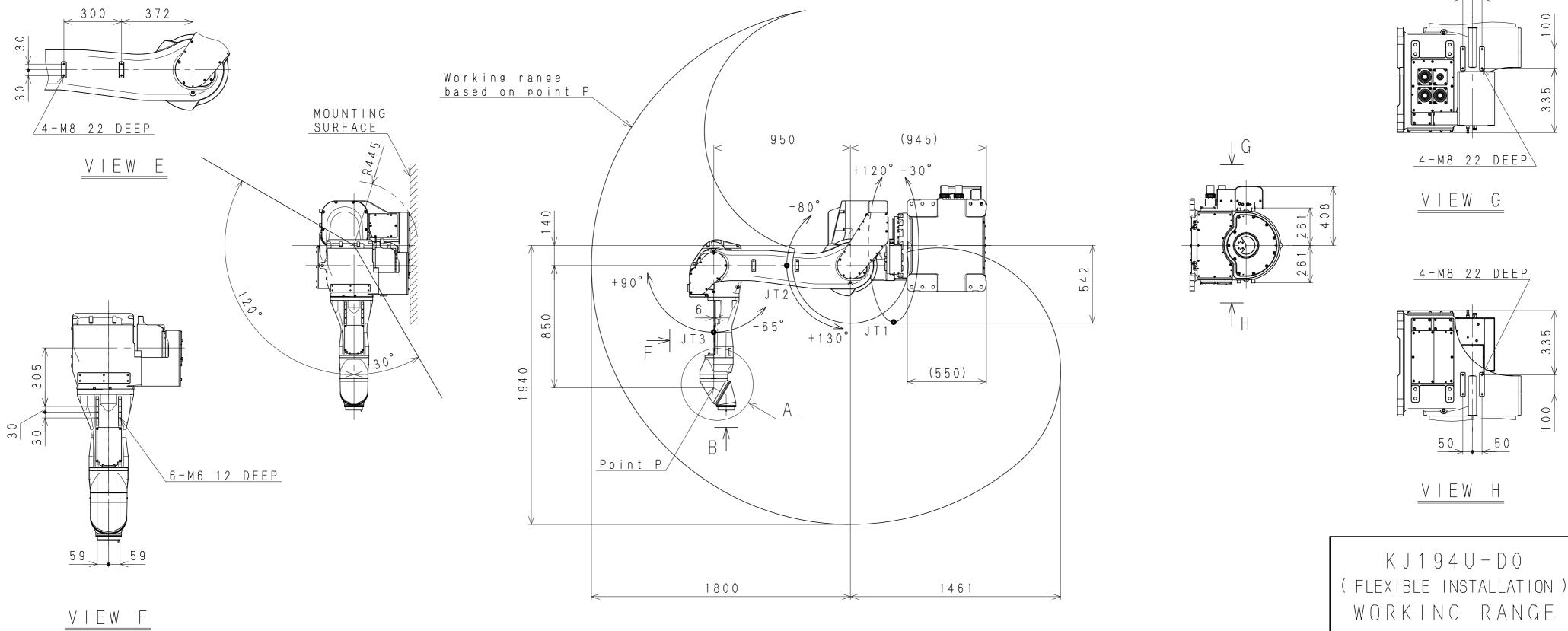


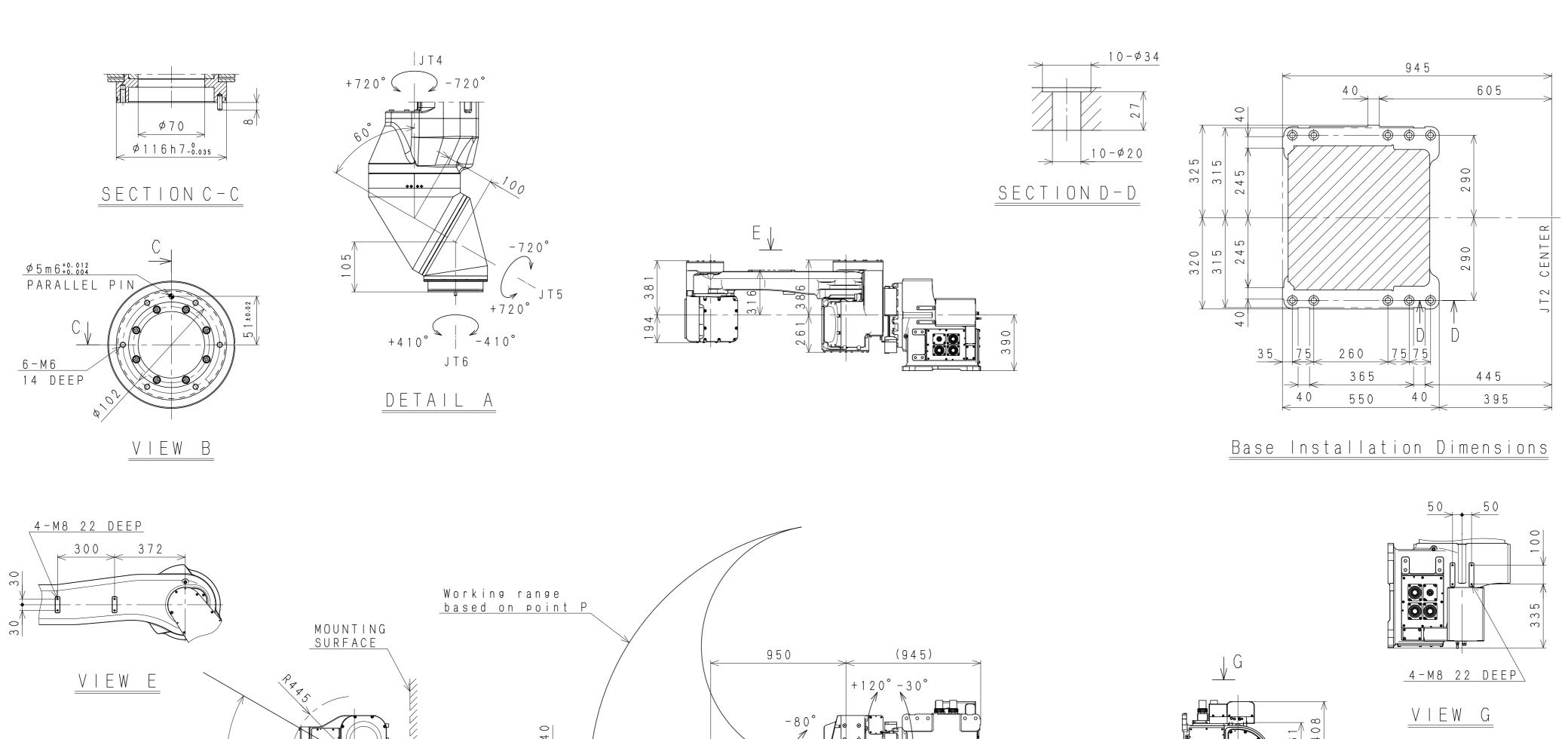


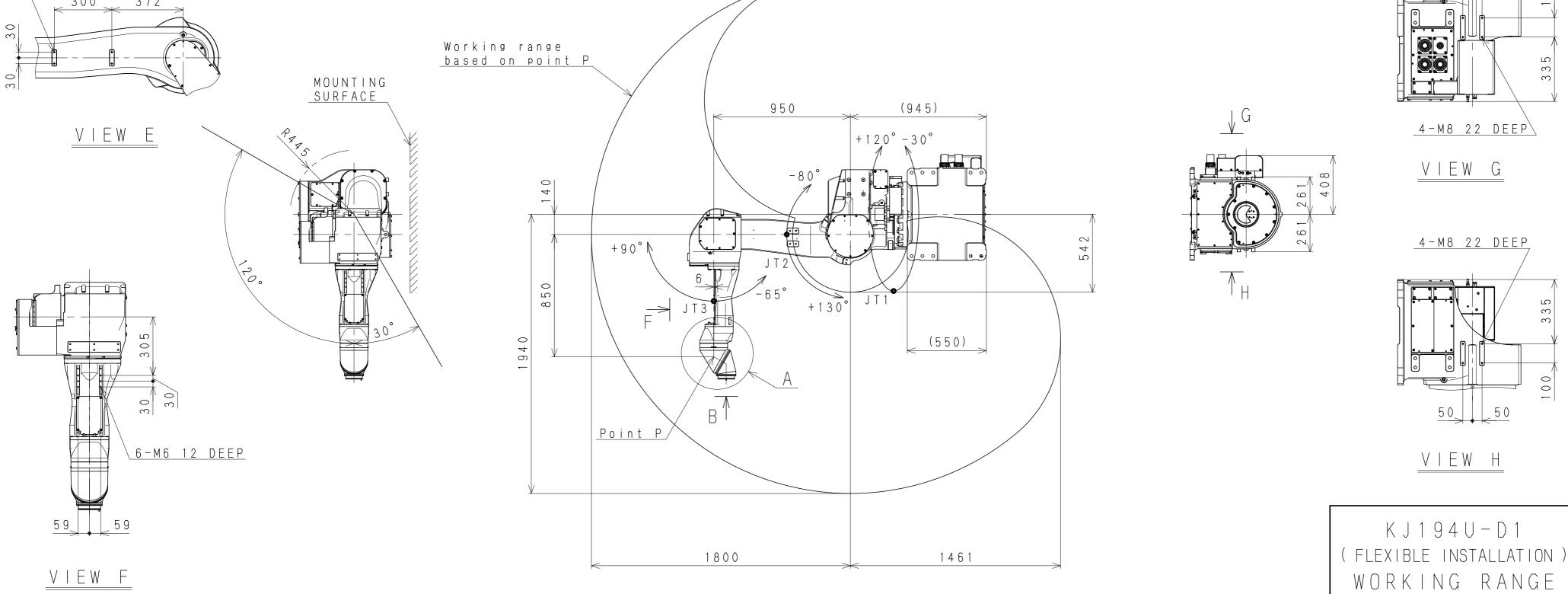


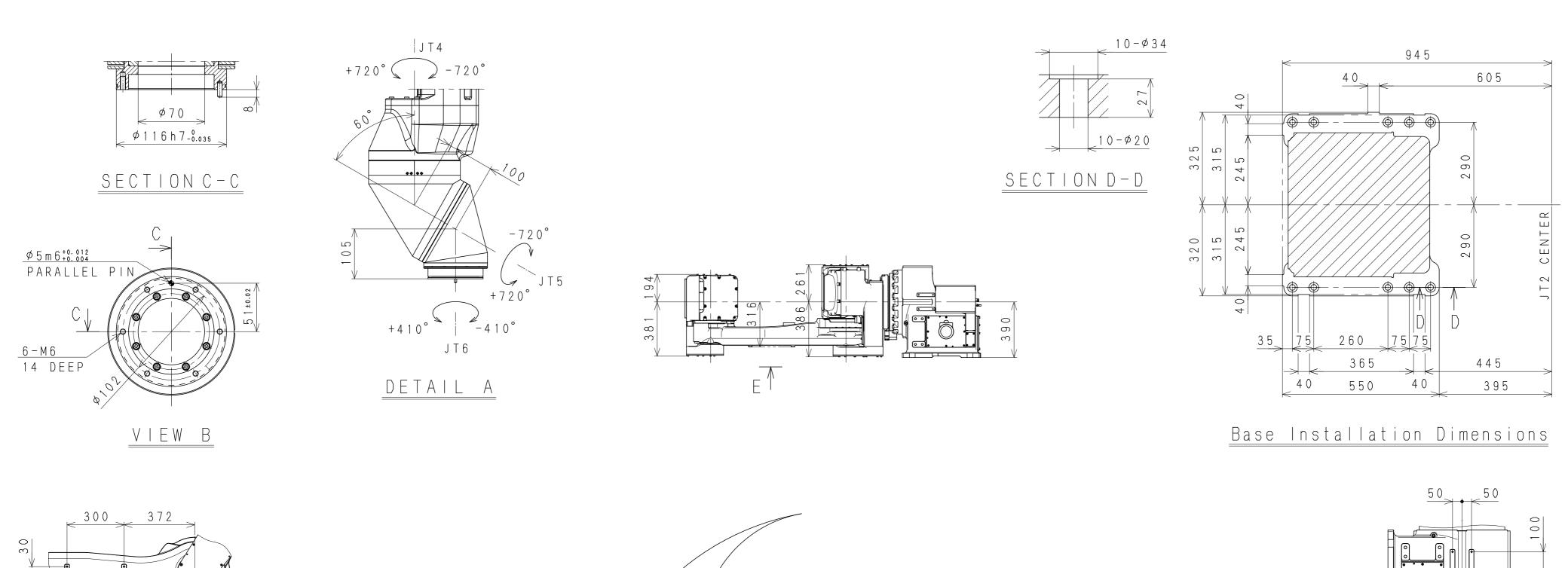


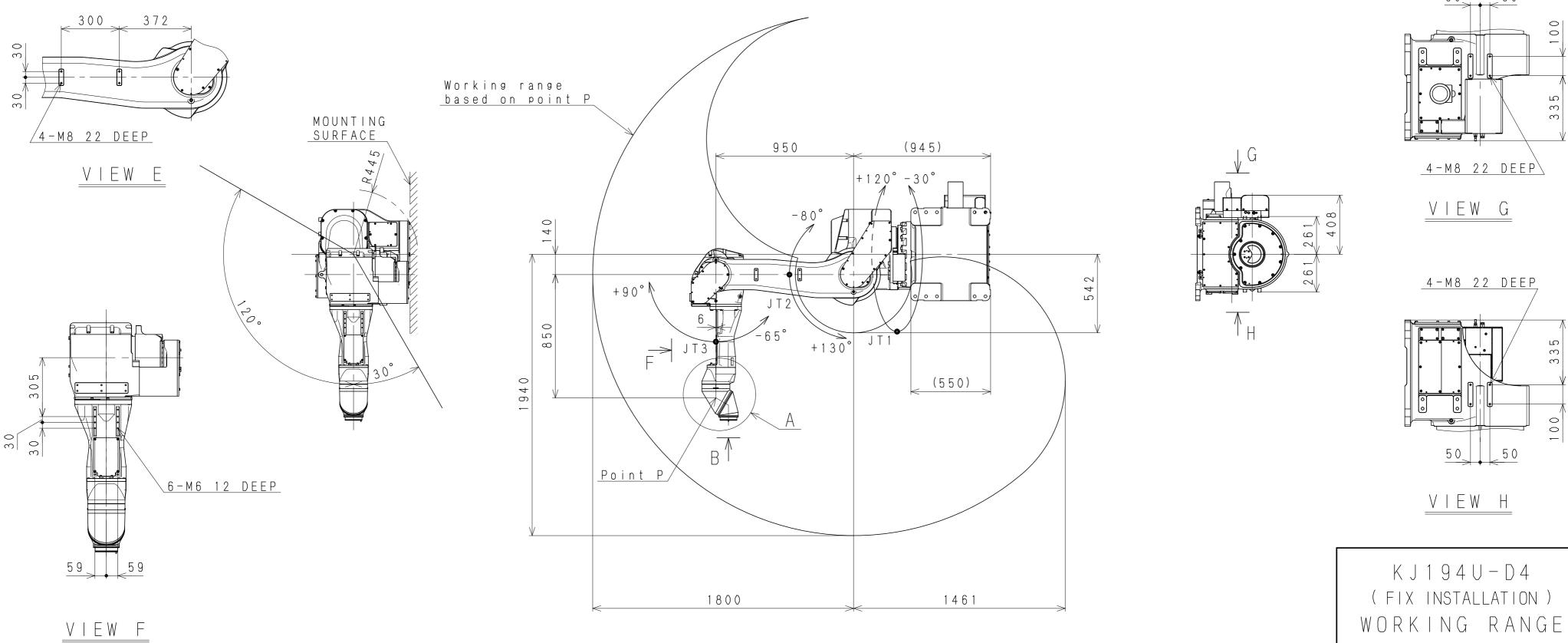


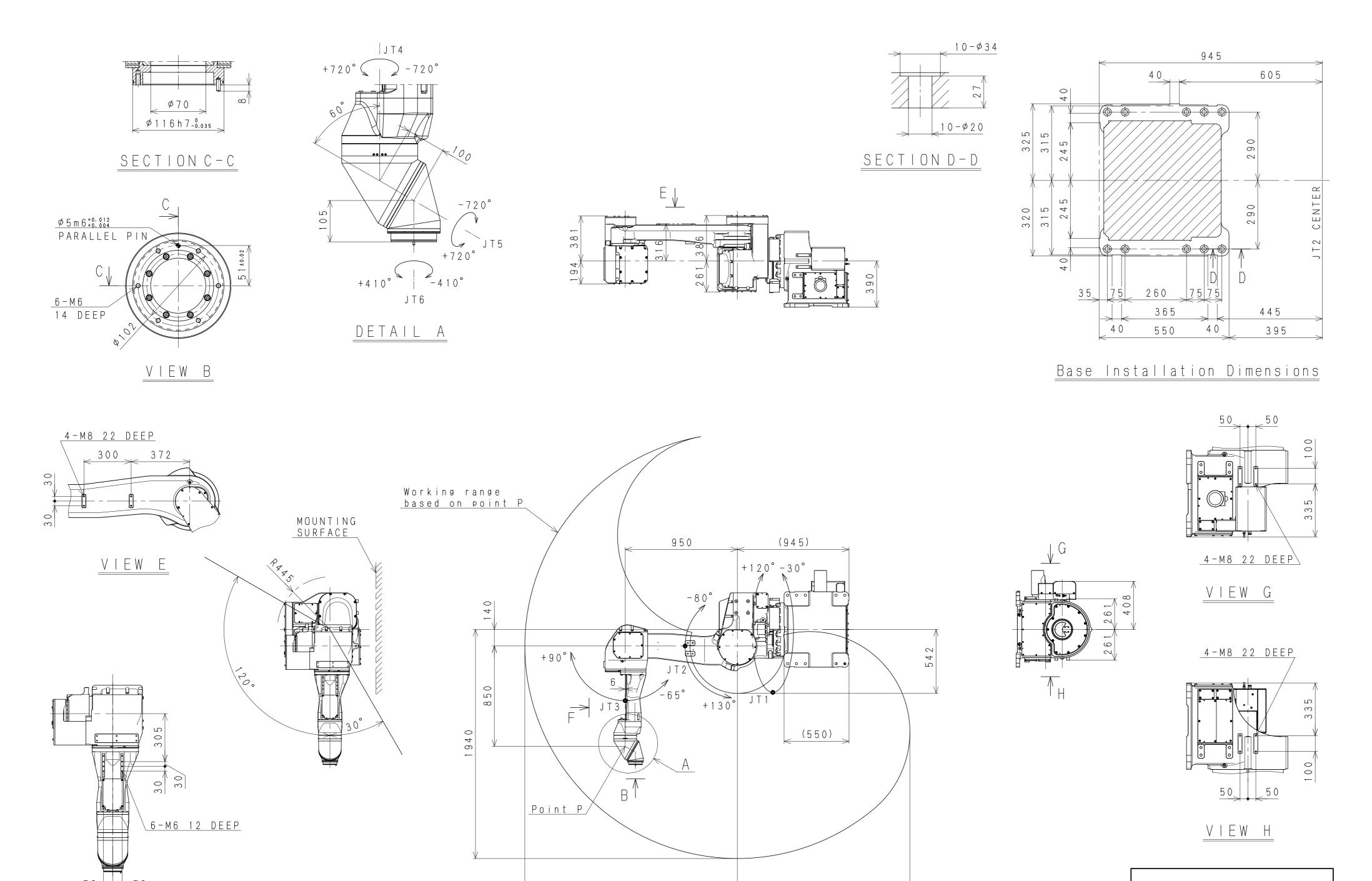










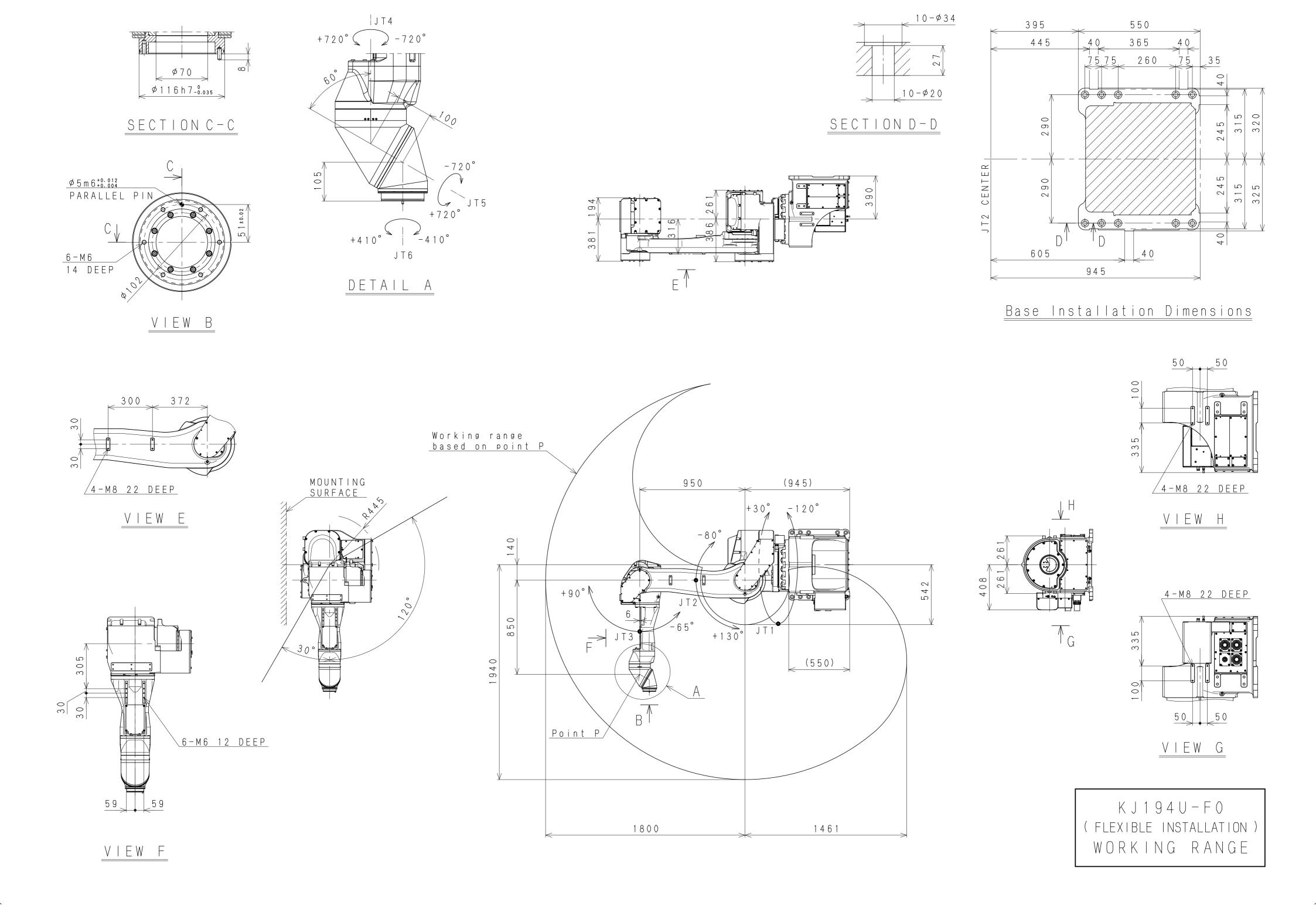


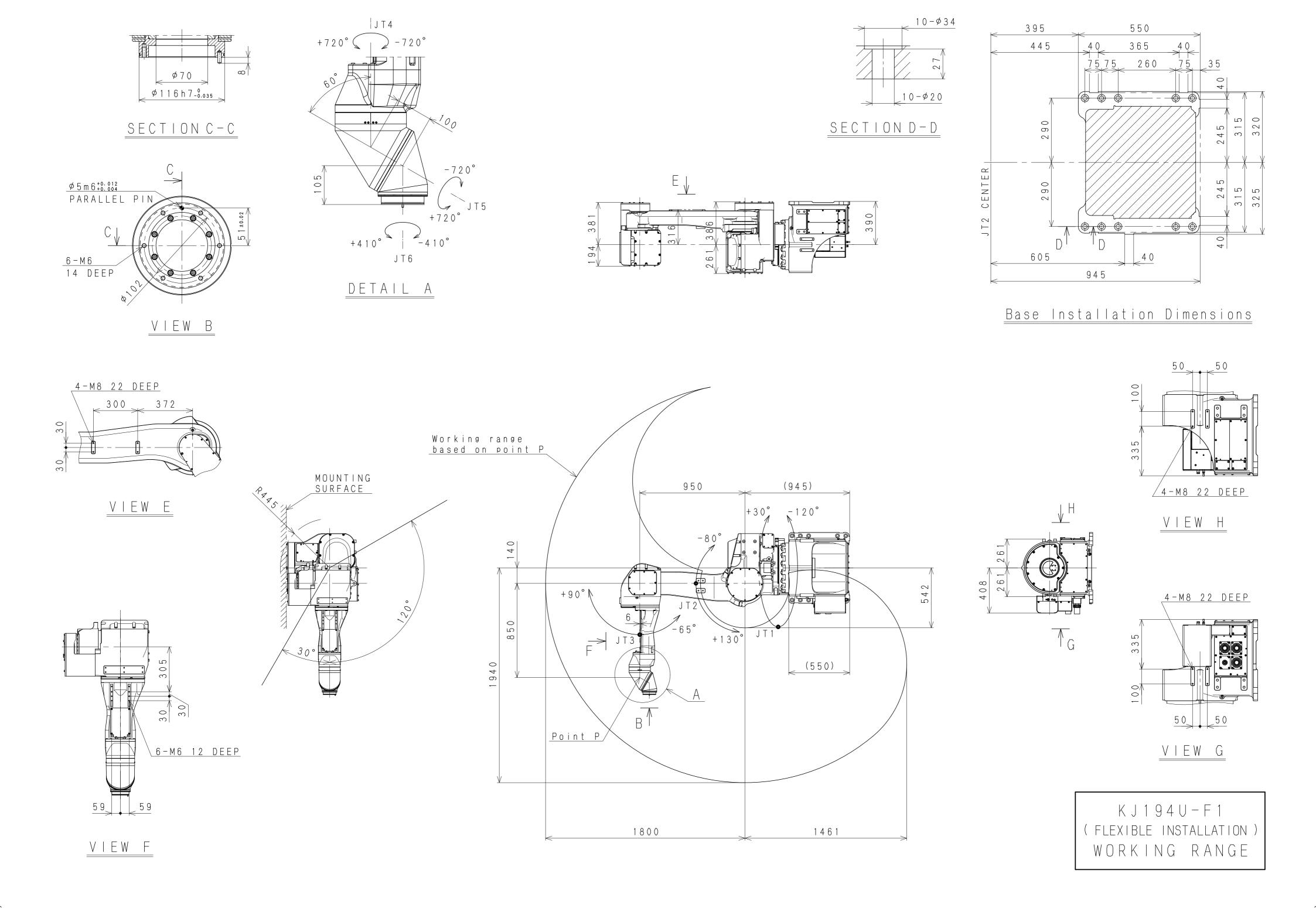
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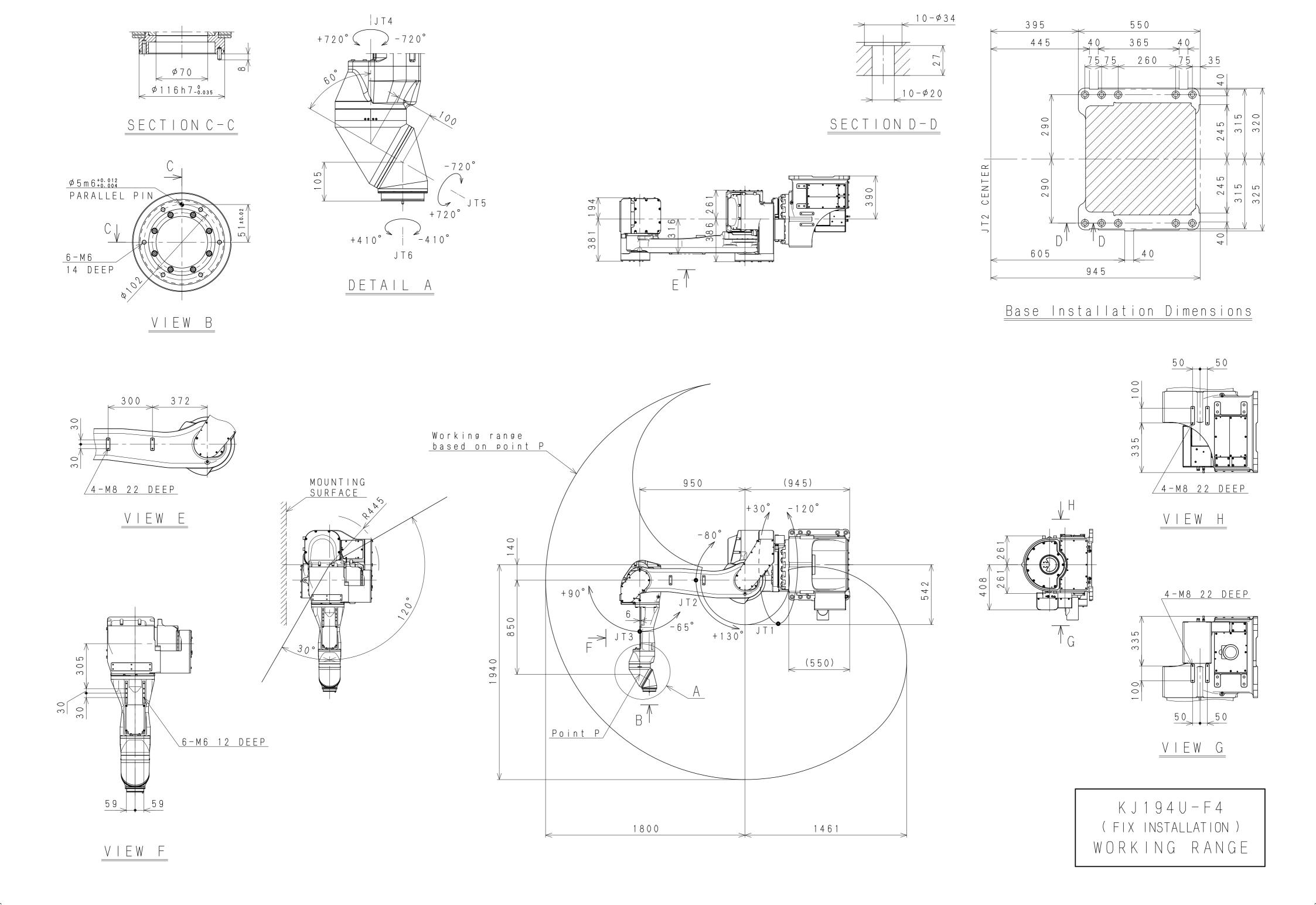
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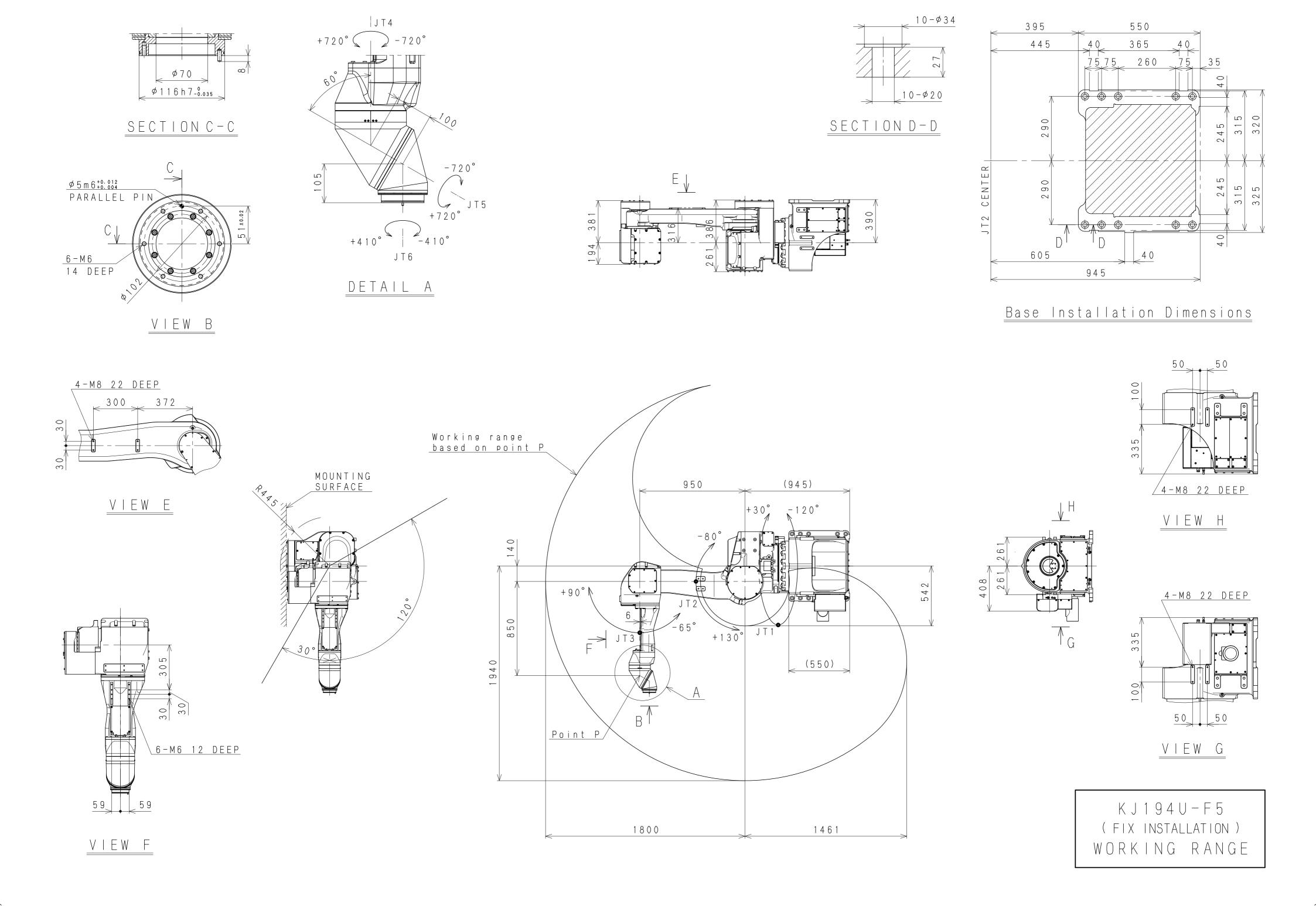
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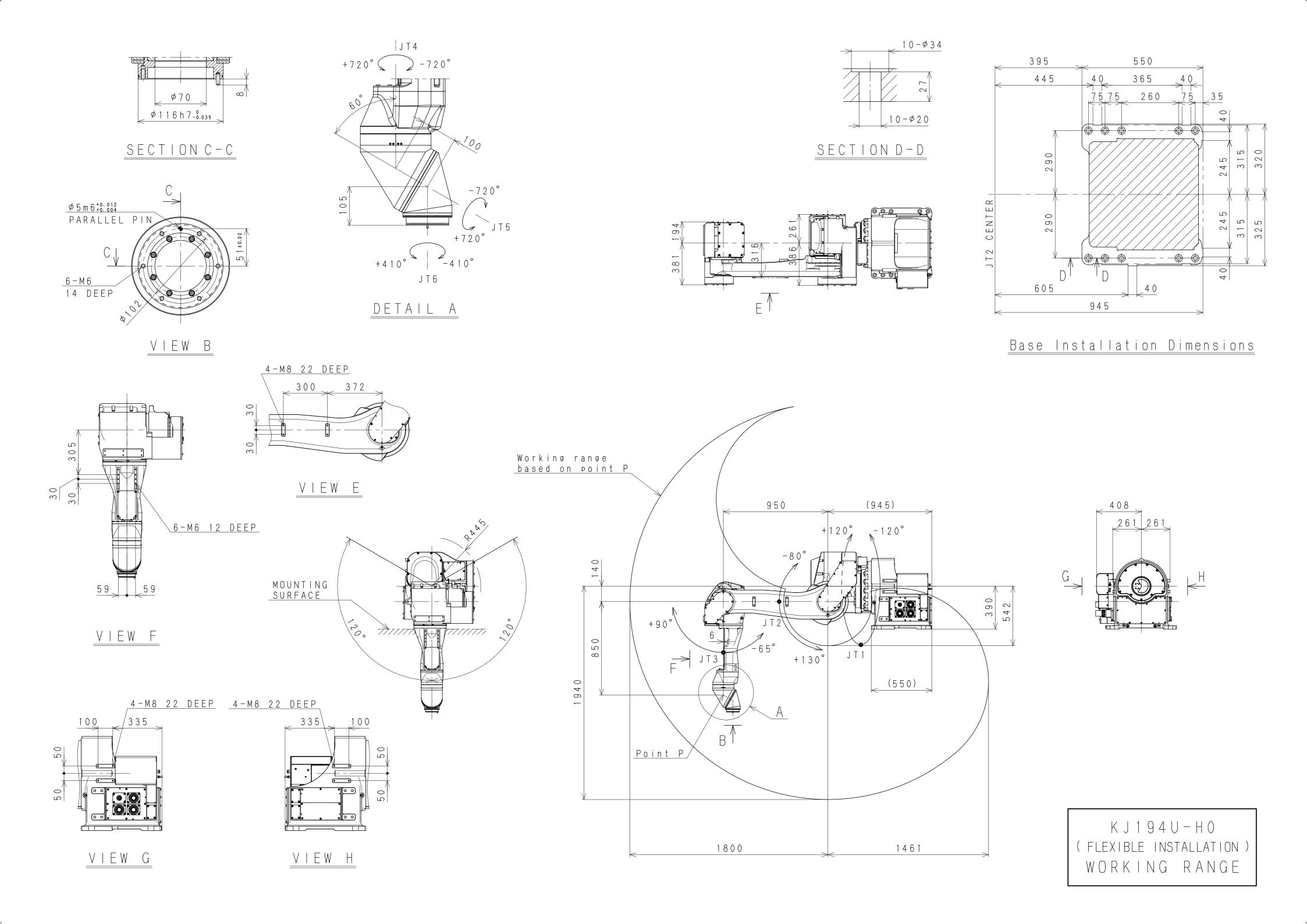
KJ194U-D5 (FIX INSTALLATION) WORKING RANGE

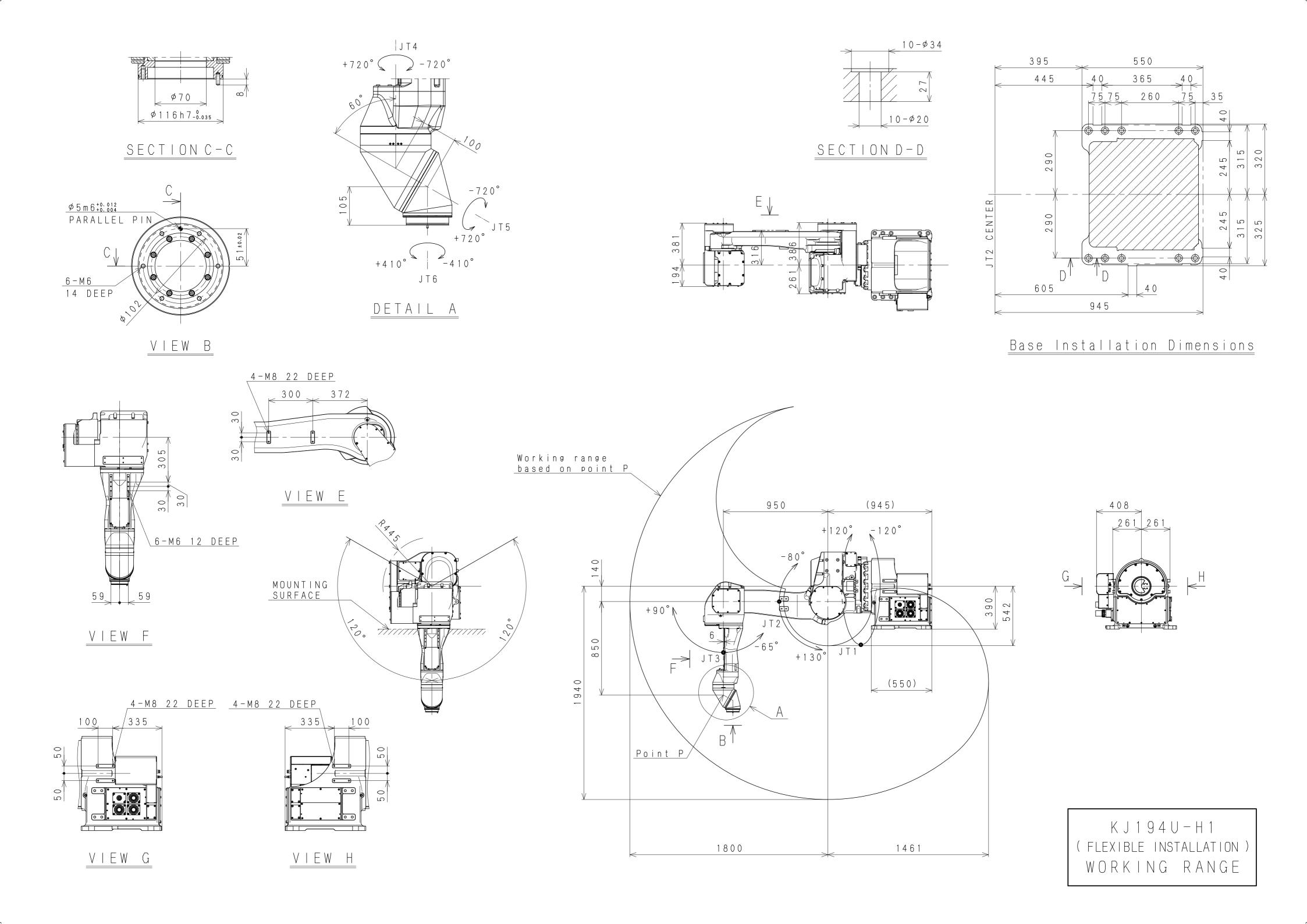


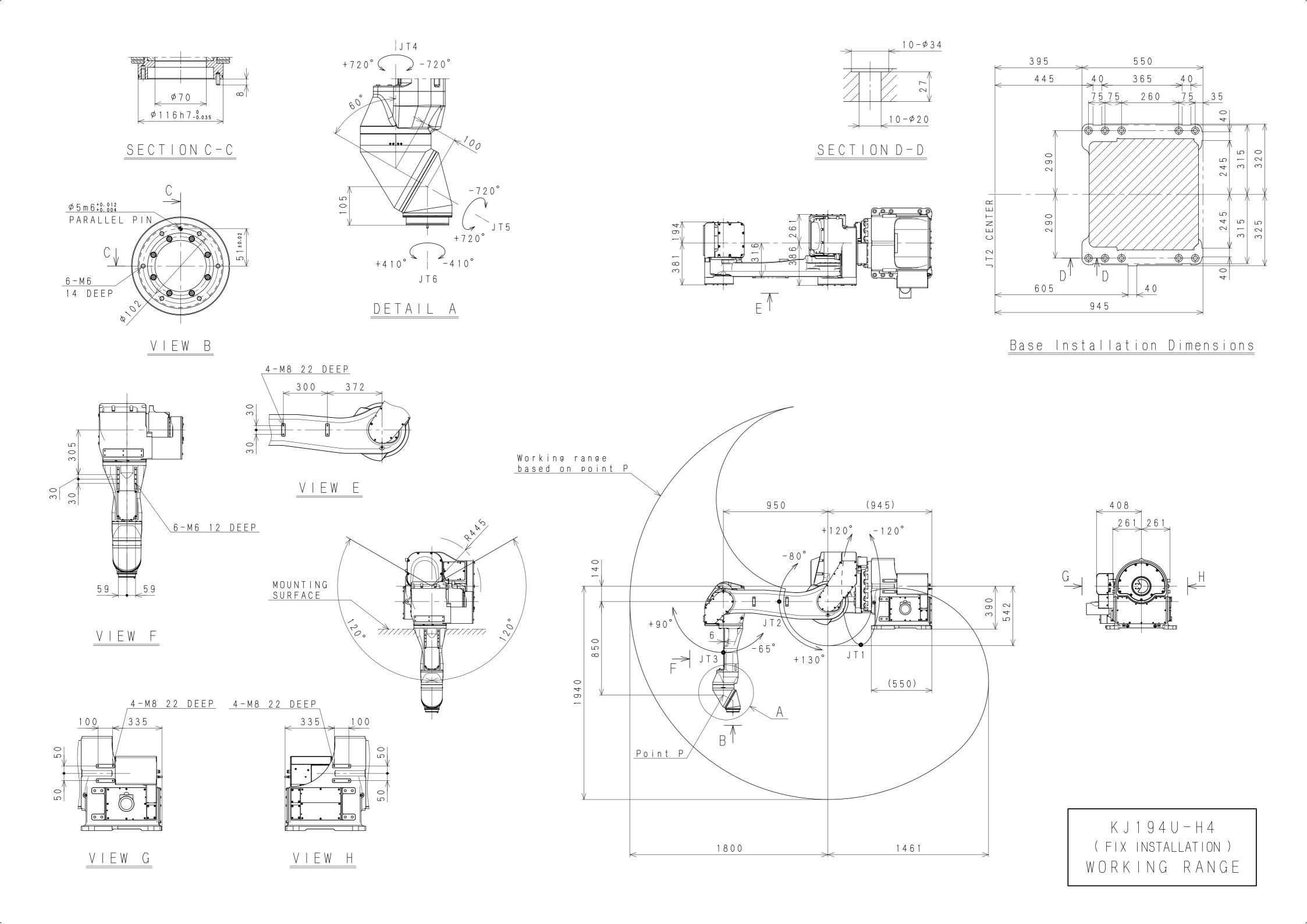


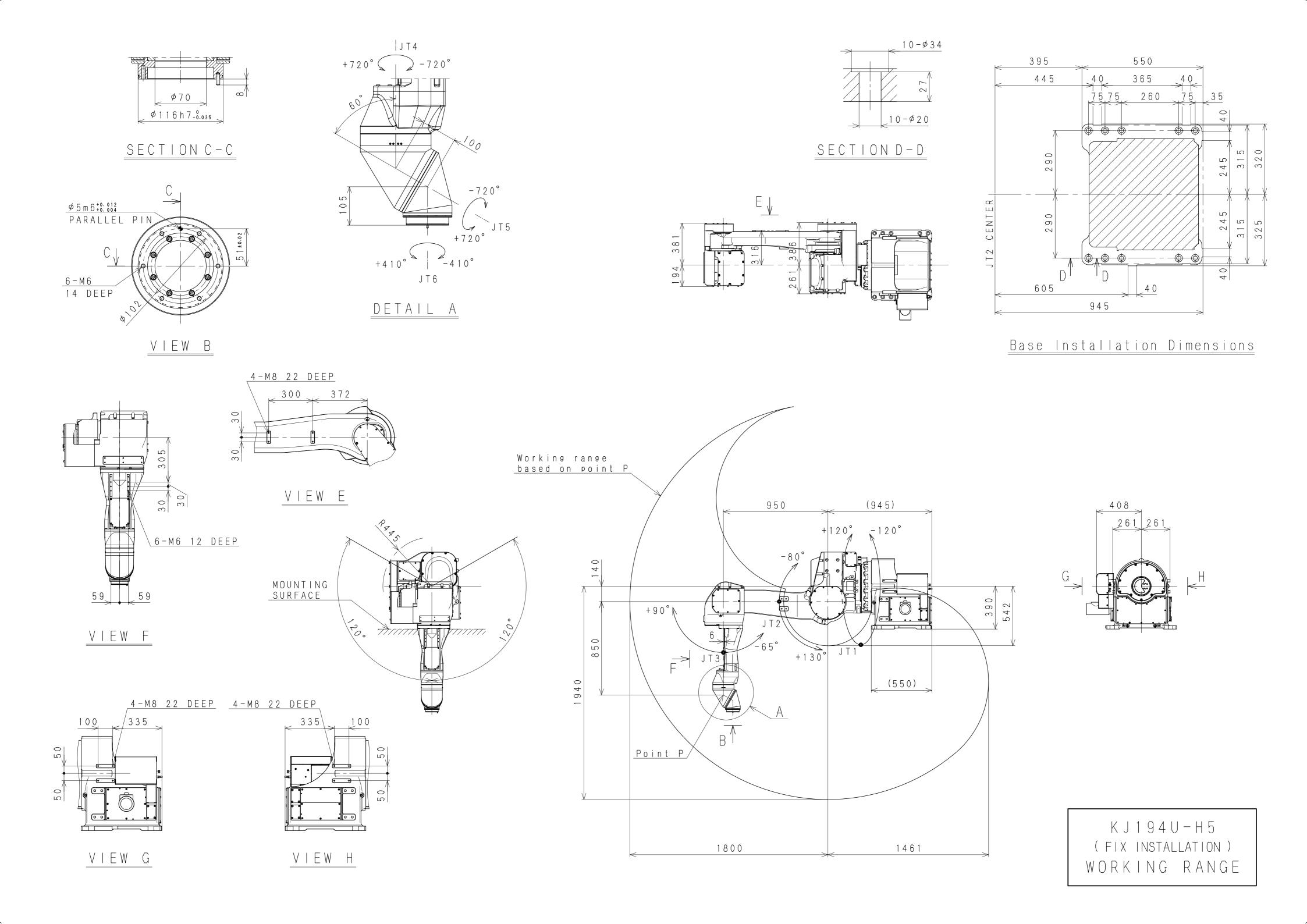












E35/E37 CONTROLLER MASS: 170Kg 550 500 **@** • Ŕ 1400 ۰ ٥ SIDE VIEW FRONT VIEW REAR VIEW SIDE VIEW WITHOUT CONNECTOR COVER (E35) WITHOUT CONNECTOR COVER (E37)