

Standard Specifications

CP700L-A

1st ed. 22-Oct-20

Kawasaki Heavy Industries, Ltd. Robot Business Division

Specification number: 90151-0332DEA

Materials and specifications are subject to change without notice.

Robot specifications

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1. Model	CP700L-A				
2. Type	Articulated robot				
3. Degree of freedom	4 axes				
4. Max. payload	700 kg				
5. Max. reach	3,255 mm				
6. Palletizing Capacity	Approx. 900 cycles/h				
Condition	up-down 400 mm, right-left 2,000 mm				
7. Position repeatability	±0.5 mm (wrist flange surface) conforms to ISO 9283				
8. Axis specification					
	Operating axis		Motion range		Max. speed
	Arm rotation (JT1)		±160°		75 °/s
	Arm out-in (JT2		+95°46°		65°/s
	Arm up-down (J7		+ 15° 110°		65°/s
	Wrist twist (JT4)		±360 °		170°/s
9. Load capacity of wrist					
		Max. torque		Moment of inertia*	
	JT4 -		500 kg•		g• m ²
	Note*2 Value in this table shows allowable moment of inertia of JT4 when max. allowed torque is applied to the axis. If more detailed data is				
	required for your application, please contact Kawasaki.				
10. Mass	1,650 kg (without options)				
11. Mounting	Floor mounting				
12. Installation Environment	Ambient Temperature: 0 - 45 °C				
	Relative Humidity: 35 - 85 % (with no dew condensation)				
13. Color	Munsell 10GY9/1 equivalent				
14. Built-in utilities	Air tube to operate the hand (ϕ 12 × 2 line)				
15. Options	Mechanical Stopper Adjustable stopper JT1				
	Valve harness		8 point		
	Sensor harness		12 point		
	Fork Pocket				
	Air cleaning equipment				
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Consult Kawasaki about maintenance parts and spare parts.

