



Standard Specifications

RS005N-A

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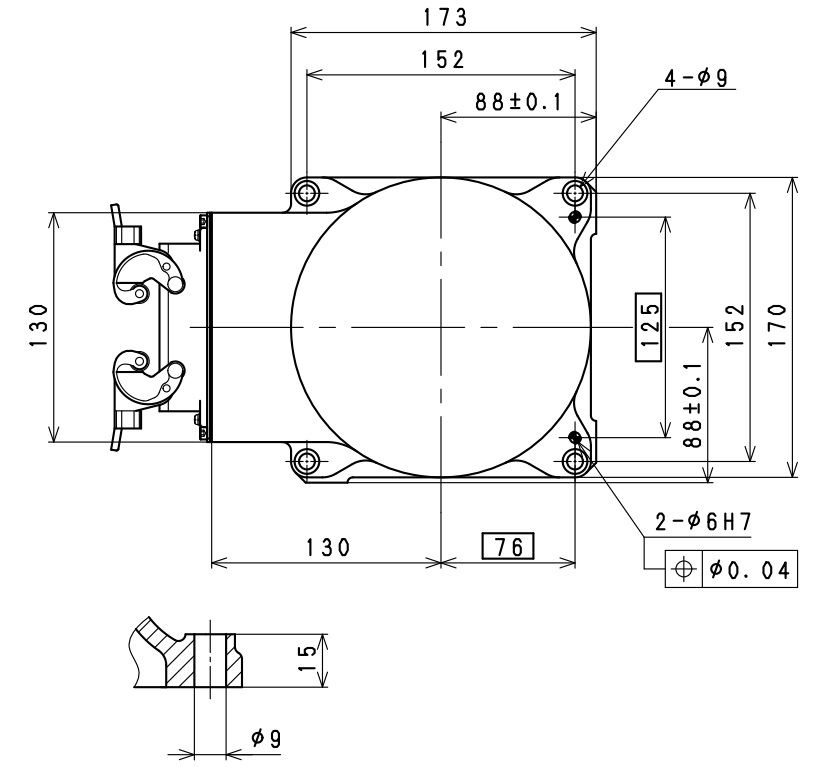
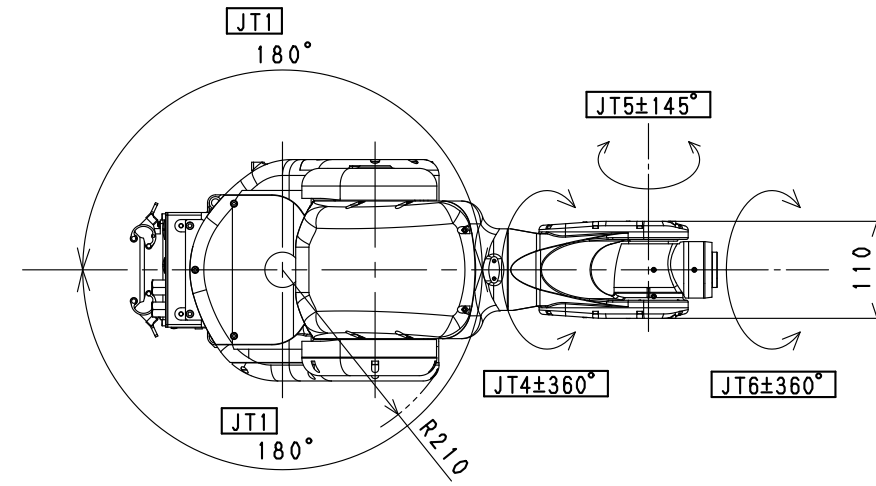
Kawasaki Heavy Industries, Ltd.
Robot Business Division

Specification number : 90151-0185DEB

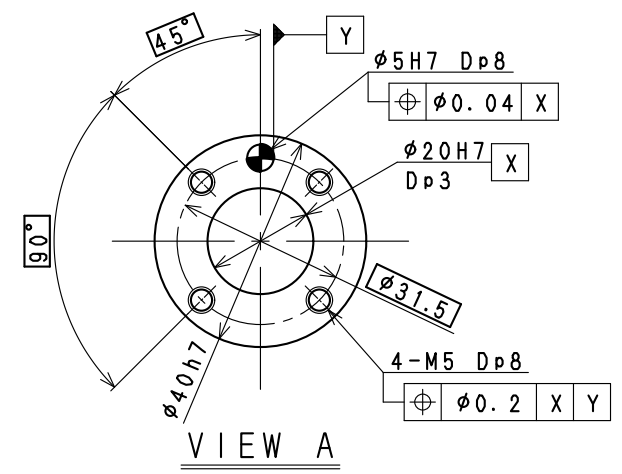
Robot specifications

1. Model	RS005N-A																							
2. Type	Articulated robot																							
3. Degree of freedom	6 axes																							
4. Max. payload	5 kg																							
5. Max. reach	705 mm																							
6. Position repeatability	±0.02 mm (wrist flange surface) conforms to ISO 9283																							
7. Axis specification	<table border="1"> <thead> <tr> <th>Operating axis</th> <th>Motion range</th> <th>Max. speed</th> </tr> </thead> <tbody> <tr> <td>Arm rotation (JT1)</td> <td>±180 °</td> <td>360 °/s</td> </tr> <tr> <td>Arm out-in (JT2)</td> <td>+135 ° - -80 °</td> <td>360 °/s</td> </tr> <tr> <td>Arm up-down (JT3)</td> <td>+118 ° - -172 °</td> <td>410 °/s</td> </tr> <tr> <td>Wrist swivel (JT4)</td> <td>±360 °</td> <td>460 °/s</td> </tr> <tr> <td>Wrist bend (JT5)</td> <td>±145 °</td> <td>460 °/s</td> </tr> <tr> <td>Wrist twist (JT6)</td> <td>±360 °</td> <td>740 °/s</td> </tr> </tbody> </table>		Operating axis	Motion range	Max. speed	Arm rotation (JT1)	±180 °	360 °/s	Arm out-in (JT2)	+135 ° - -80 °	360 °/s	Arm up-down (JT3)	+118 ° - -172 °	410 °/s	Wrist swivel (JT4)	±360 °	460 °/s	Wrist bend (JT5)	±145 °	460 °/s	Wrist twist (JT6)	±360 °	740 °/s	
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9. Mass	34 kg (without options)																							
10. Mounting	Floor or Ceiling mounting																							
11. Installation Environment	Ambient Temperature: 0 - 45 °C Relative Humidity: 35 - 85 % (with no dew condensation)																							
12. Color	Munsell 10GY9/1 equivalent																							
13. Degree of protection	Wrist: IP67 equivalent Arm: IP65 equivalent																							
14. Built-in utilities	Pneumatic piping (φ6 × 2 lines)																							
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Consult Kawasaki about maintenance parts and spare parts.



Installation Dimensions



RS005N
WORKING RANGE

