Break the mold of "Appearance inspection = visual inspection"

Scanning appearance inspection system

Achieves high-speed inspections of complex curved surfaces using Kawasaki robots



Past appearance inspection

 \cdot Mainly by visual inspection

• Automated inspection with area cameras also requires a long time to start up the system and complete inspections.

Lack of inspectors and variation in judgment

Future appearance inspection

•Kawasaki Robot with line scan camera achieves quick startup and completion of inspections

Realizes variation-free inspection at high speed 24/7/365

Features

Continues scanning even

on curved surfaces Scans complex surfaces smoothly like a copy machine.

Reduces cycle times to 1/10

cycle times more significantly than area cameras.

Reduces startup time to 1/6

This makes the system startup time far shorter than that with area cameras.

cycle times image

Area camera with onventional robotIntermittent photographyReduces



Powering your potential





Reduces cycle times to 1/10!

Break the mold of "Appearance inspection = visual inspection"

Scanning appearance inspection system

Automates processes from appearance inspection to sorting at high speed in small spaces



Features

Automates appearance inspection that requires only a workspace for one person

Saves spaces (required dimensions: 2 × 1 m) by fixing the camera for handling workpieces.

Powering your potential

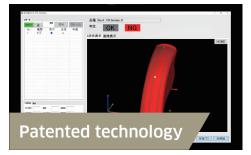
Inspects small workpieces with complex curved surfaces at high speed.

Line scan cameras achieve high-speed visual inspection of small workpieces having complex curved surfaces.

Sorts good and defective workpieces

After completing an inspection, the robot also sorts good and defective workpieces.

Identifies defective sections for improved yield



- A 3D Viewer displays defective sections
- ·Marks actual workpieces
- Improves yield by accumulating and analyzing data on defective workpieces
- •Storage of defective data ensures traceability